

## Data Handling and Sharing

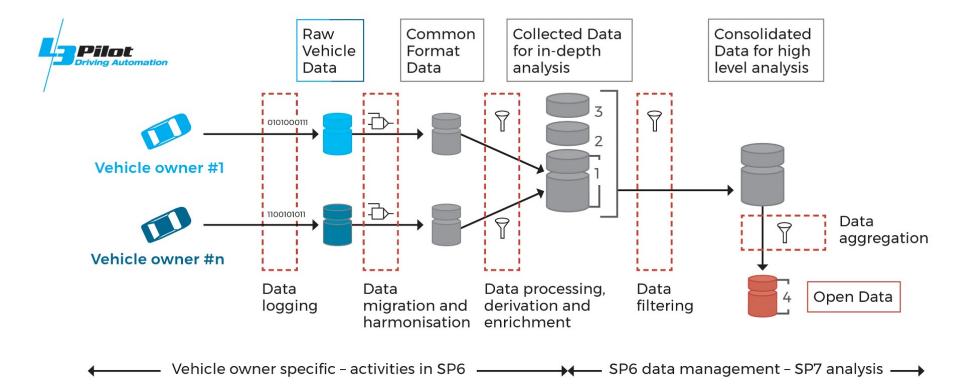
L3Pilot Final Event

#### Johannes Hiller, ika RWTH

On behalf of data team (Natalia, Erik, Frederic, Sami, Markus and many more)



## L3Pilot Common Data Format Data Flow



#### Categories of data:

- 1 Derived Vehicle Data (CAN, GPS, PIs, video, and/or video annotations)
- 2 Subjective Data (interviews, questionnaires, simulator studies)
- 3 External Data (weather, map, ...)
- 4 Open Data (aggregated data)

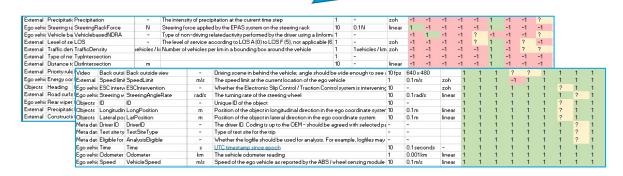




### L3Pilot Common Data Format Signal Requirements

RQ Level 3	Logging requirements I sensors available	Performance Indicators Required				
The ADF will work as expected in its planned driving and traffic scenario	Vehicle data • additional data sources (if information are not provide by the car)	System status, distribution of longitudinal velocity per driving scenario and situation variables				
How often do unexpected take-over requests occur?	Vehicle data + additional data sources (if information are not provide by the car)	System status, distribution of longitudinal velocity per driving scenario and situation variables				
Does the function initiate a take-over request if required by the boundaries of the ADF?	Vehicle data + additional data sources (if information are not provide by the car)	System status, distribution of longitudinal velocity per driving scenario and situation variables				
What is the impact of ADF on the frequency of traffic violations?		Distribution of difference between speed and speed limit, distribution of distances to other objects, frequency of overtaking manoeuvres in overtaking prohibitions				
How do take-over situation affect the driving dynamics of the vehicle?		Distribution of lateral and longitudinal acceleration and velocity				
What is the impact of ADF on longitudinal acceleration in defined driving situations?		Distribution of logitudinal acceleration				
What is the impact of ADF on lateral acceleration in defined driving situations?		Distribution of lateral acceleration				

Research questions specified with logging requirements by Methodology Partners



Signals derived and sent out to discussion with Pilot Leaders

Available signals assessed and fixed for Common Data Format

ADFunctionActive	-	1	1	1	1	1	1	1	1	-1	1	1
ADFunctionAvailable	-	1	1	1	1	1	1	1	1	1	1	1
TOR	-	-1	-1	1	1	1	1	1	1	-1	?	1
FrontWiperStatus	-	1	1	1	1	1	1	1	1	1	1	1
FrontFogLightStatus	-	1	1	1	1	1	1	1	1	1	1	1
RearFogLightStatus	-	1	1	1	1	1	1	1	1	1	1	1





### L3Pilot Common Data Format Requirements

- Portability
  - Transfer of data from vehicle owner to analysis partner
- Compatibility
  - Many different platforms used by vehicle owners
  - Many different languages used in development and analysis









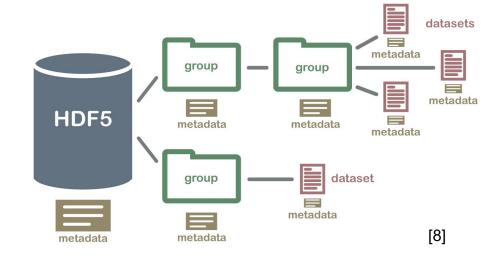






# L3Pilot Common Data Format HDF5

- Many file formats were checked
- Hierarchical Data Format (HDF) was selected
- Portable, binary format
  - Compression optional
- Open source and free to use
- Available for many platforms & languages
  - Windows, Linux, ...
  - Matlab, C/C++, Python, Java, ...







### L3Pilot Common Data Format Structure with Vehicle Signals

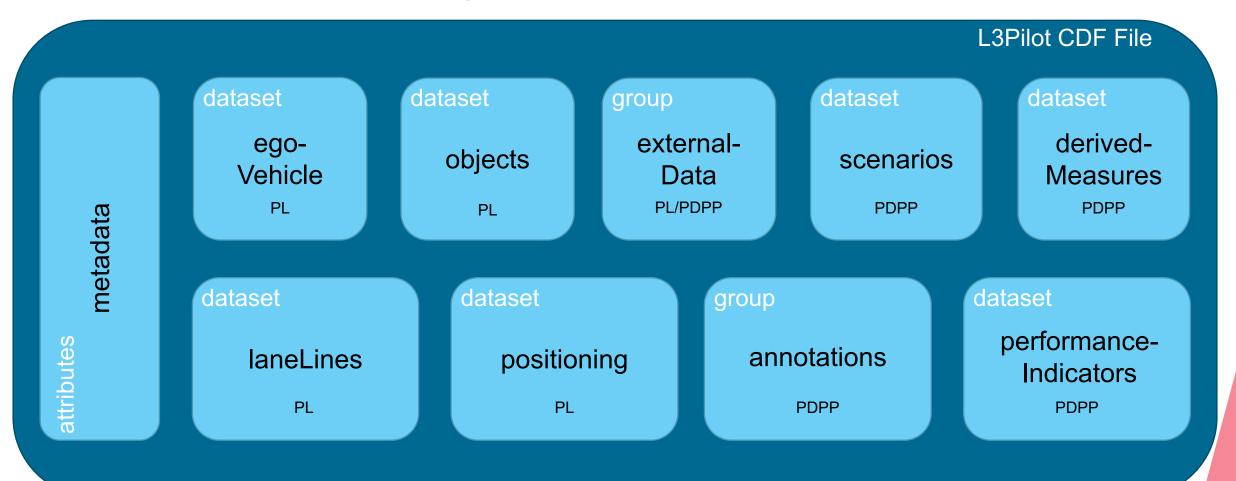
L3Pilot CDF File dataset dataset egoobjects Vehicle PL PL metadata dataset dataset attributes **laneLines** positioning PL PL

PL – Pilot Leader





### L3Pilot Common Data Format Structure with Vehicle Signals



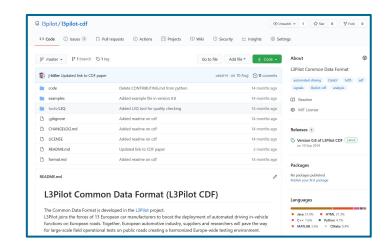
PL – Pilot Leader

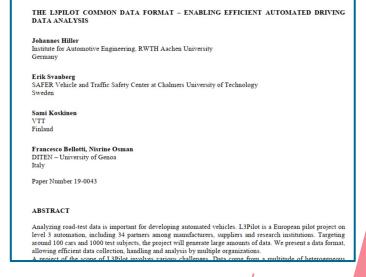


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#### L3Pilot Common Data Format (L3Pilot CDF)

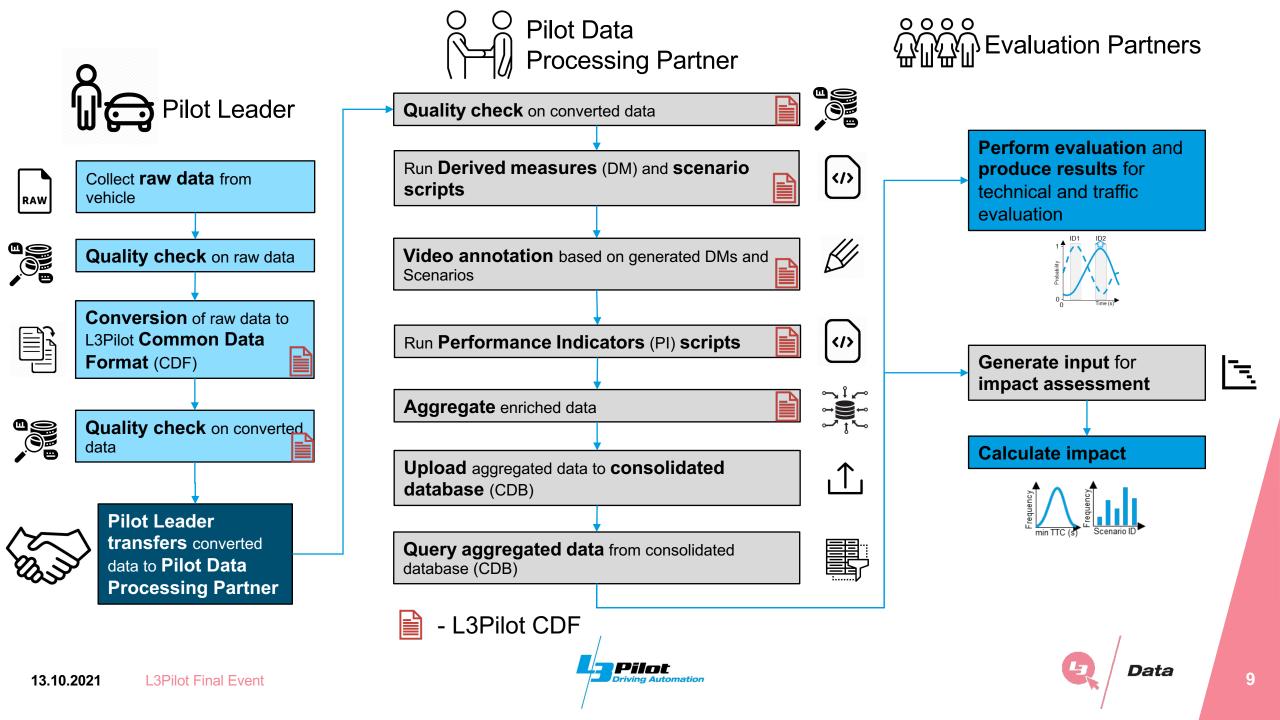
- The CDF is made available to the public via Github: *I3pilot/I3pilot-cdf* The CDF is made available to the public via Github:
  - Everyone is invited to use the format and contribute to it
  - Use open source tools and formats to facilitate use in other projects
- Detailed information on the format can be found on NHTSA website (public access)
  - "The L3Pilot Common Data Format Enabling Efficient Automated Driving Data Analysis"







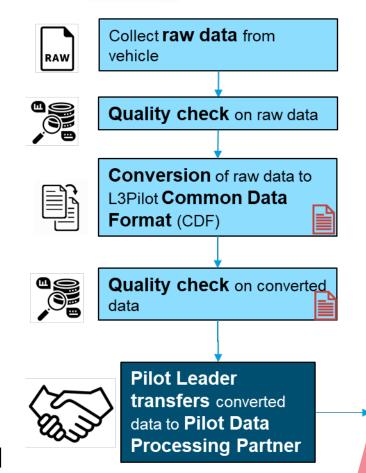




#### **Data Quality Checks**

Pilot Leader

- List of common data quality mishaps and tests
  - Best practices
  - Pilot Leaders encouraged to follow checks
- Consisted of 28 mandatory and 4 optional checks
  - Sensors, Enumerations and Format
  - Aggregated Data and Scenarios
- In the end, some data quality issues were still discovered during evaluation phase
  - Very time-consuming, if vehicle data must be re-processed

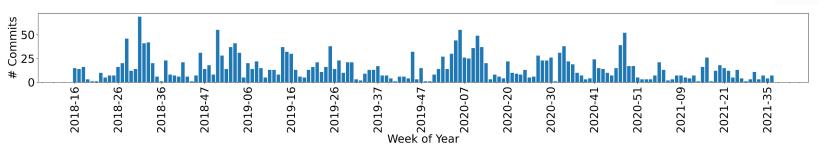


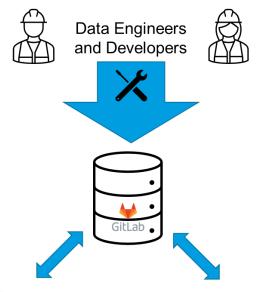




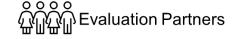
# L3Pilot Data Tools Development

- Various software tools were developed and improved within L3Pilot
- 2481 single commits to the Gitlab Server in 21 repositories
  - Over 2 commits per day on every weekday in project duration
- Nearly 700 issues opened, discussed, fixed and closed
- International team of over 20 developers







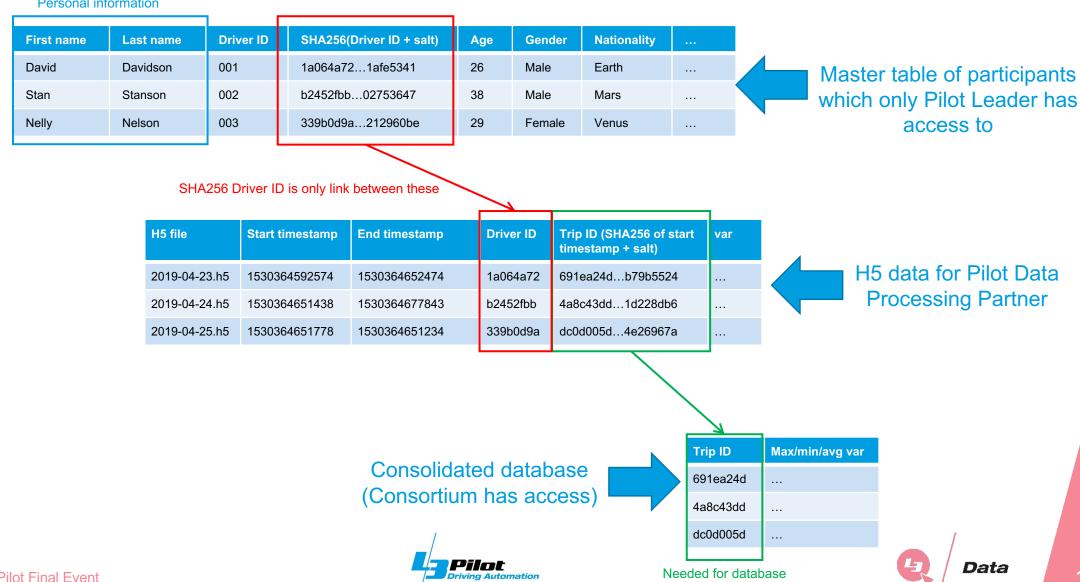






#### **Pseudonymization Process**

#### Personal information



mechanics

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Confidentiality

Detail

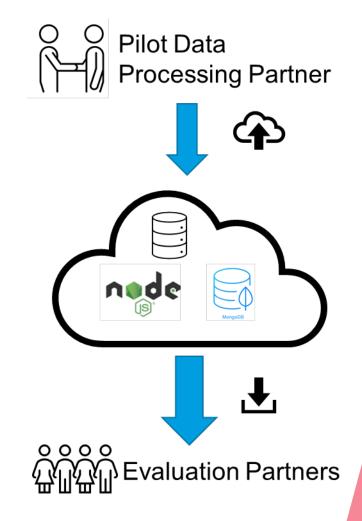
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#### **Consolidated Database** Overview

- Interfaces for storing, managing and retrieving vehicular measurements.
- Big data management based on non-relational database
- Includes run-time checks for data integrity
- User roles, to guarantee the needed confidentiality levels
- Made available through cloud provider
- Tools for accessing and up- and downloads available to evaluation partners
- The L3Pilot CDB is a configured instance of the open source Measurify IoT development framework: <a href="https://measurify.org/">https://measurify.org/</a>







#### Conclusions

Collaborative work of over 20 international developers

 Developed a harmonized Common Data Format used by pilot leaders and pilot data processing partners

Made Common Data Format open source and available to interested parties

 Developed a set of harmonized tools for converting, transferring and evaluating piloting data







#### Thank you for your kind attention.

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