

EUCAD 2021 BO4 Key Vehicle Technologies for CCAM

Vehicle Automated Functions Challenges

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With the Motorway Chauffeur the car adapts to various traffic conditions. It follows the lane and adjusts speed considering various factors such as keeping a safe distance to the vehicle in front or following the speed limit. If a preceding slower vehicle is detected the car overtakes automatically as soon as it is safely possible. MOTORWAY CHAUFFEUR



On motorways and similar roads the car takes over the driving in traffic jam up to 60 km/h. When the detection of slow driving vehicles in front indicates a traffic jam, activated. In some instances, the car changes the lane to react to a slower vehicle ahead or infrastructural reasons like exit anes. - Pilot TRAFFIC JAM CHAUFFEUR SAE LEVEL 0 1 2 3 4



With the Urban Chauffeur the vehicle automatically follows the lane, starts and stops and handles overtaking within cities. When coming to a crossing the car handles right and left turn, recognises on-coming traffic and vulnerable road users such as pedestrians, and selects the correct crossing path, even if no lane marking is present.

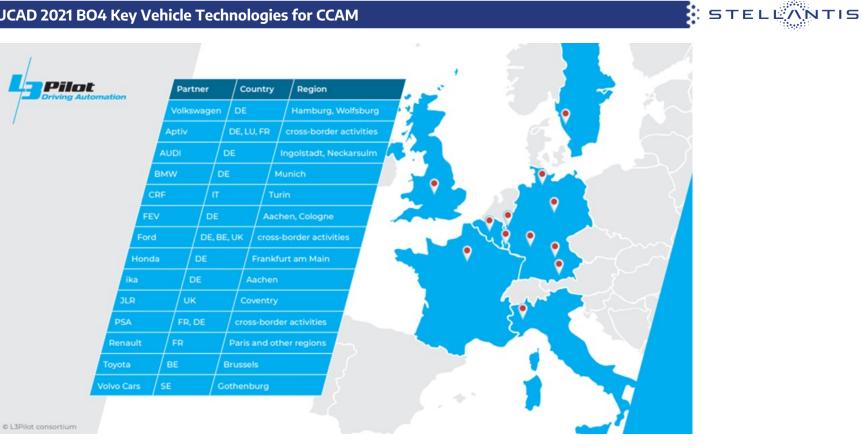
URBAN CHAUFFEUR

L3Pilot is co-funded





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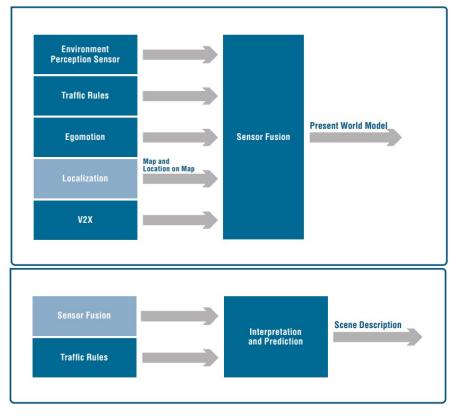
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PERCEIVE static and dynamic road actors / objects

Pilot Driving Automation

PREDICT the future behaviors of road actors



Challenges identified in L3Pilot can be mapped within the key components identified in the White Paper:

"Safety First for Automated Driving" (ed. Sep. 2019)





HI

Connectivity for Vehicle Automation









Machine Learning for Vehicle Automation



SENSING Large dataset of automatically annotated traffic scenarios (from Camera, Radar, LIDAR) to train supervised machine learning algorithms for road actors classification and tracking.

PLANNING Machine Learning algorithms for maneuvers selection and trajectory planning.







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